



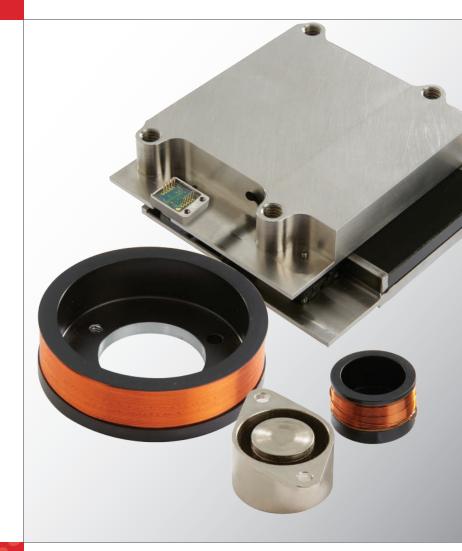
Applimotion *Motors & Actuators*

PRODUCT DATA SHEET

Juke[™] Series Motors

Compact Voice Coil Motors for Highly Dynamic Motion Profiles

The Juke Series enables OEMs to move light payloads with high acceleration and dynamic motion profiles.



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Accelerate Your Innovation.

Juke[™] Series Motors

Compact Voice Coil Motors for Highly Dynamic Motion Profiles



Swift and Simple.

The Juke Series motors are ideal for optics, laser scanning, pick and place, medical probes, hexapods and other applications that require highly dynamic moves of light payloads over short distances.

Low electrical and mechanical time constants, low moving mass and no cogging allow for extremely high accelerations and precise control of position, velocity or force. No commutation is required, simplifying wiring and increasing system reliability.

Moving magnet and moving coil configurations make it easy for the Juke Series to be tightly integrated into compact, lightweight precision assemblies. Flat and circular body form factors are offered for linear applications. Rotary and partial segment designs are also available.

All models are compatible with a wide range of controllers and drives. Windings and form factors can be customized to meet application requirements.

Benefits

- Compact size, high force-to-weight ratio
- High acceleration
- Simple wiring and control
- Smooth, accurate motion
- Easy integration into system design
- Compatible with wide range of drives and controllers
- Custom windings and form factors available to meet application requirements

SPECIFICATIONS	UNITS	FLAT BODY VOICE COILS	CIRCULAR BODY VOICE COILS
Peak Force:	Ν	8 to 175	5 to 46
Stroke:	mm	6 to 20	2 to 40
Continuous Power:	\mathbb{W}	25 to 65	3 to 18
Width:	mm	55 to 140	19 to 32 (OD)
Length:	mm	40 to 120	25 to 38

Product groups listed and corresponding data are provided as a reference. Actual motor attributes are model and configuration specific. Standard and custom models are available within each group. Peak torque output is based on a 3:1 peak to continuous current ratio in the amplifier, and is based on limited duty cycle. Specifications subject to change.



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Juke Round Body Voice Coil Motors

	1617	1395	1716
Ohm	12.7	4.5	2.7
Volts	24	24	24
Amps	0.66	2.03	2.96
N/amp	6.0	7.3	16.3
Volts meter/sec	6.0	7.3	16.3
mh	2.4	0.9	1.1
Newton	10N	29.5	96.5
Newton	3.96	14.77	48.25
sec	0.00019	0.00020	0.00041
mm	5	10	10
degC/watt	15.5	7	5.5
degC	155	155	155
gram	15.2	40	42
gram	33.5	200	470
mm	300	300	300
N∕ watt ^½	1.68	3.44	9.92
	Volts Amps N/amp Volts meter/sec mh Newton Newton Sec amm degC/watt degC gram gram	Ohm 12.7 Volts 24 Amps 0.66 N/amp 6.0 Volts meter/sec 6.0 Mh 2.4 Mh 3.4 Newton 10N Sec 0.00019 Mm 5 degC/watt 15.5 degC 155 gram 33.5 mm 300	Ohm 12.7 4.5 Volts 24 24 Amps 0.66 2.03 N/amp 6.0 7.3 Volts meter/sec 6.0 7.3 Volts meter/sec 6.0 7.3 Mh 2.4 0.9 Newton 10N 29.5 Newton 3.96 14.77 sec 0.00019 0.00020 mm 5 10 degC/watt 15.5 7 degC 155 155 gram 33.5 200 mm 300 300



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Juke Flat Body Voice Coil Motors

	1235	1343	1200
Ohm	2.2	5.1	3.4
Volts	24	24	24
Amps	3.44	2.91	4.37
N/amp	2.35	10.4	36.5
Volts meter/sec	2.35	10.4	36.5
mh	0.3	4.8	4.7
Newton	7.5	31.2	284
Newton	5.0	24	142
sec	0.00014	0.00094	0.00138
mm	10.1	20	+⁄- 1.5
degC/watt	5	3	2
degC	155	155	155
gram	32	567	1198
gram	170	595	5670
mm	300	300	300
N / watt ^{3/2}	1.58	4.60	19.75
	Volts Amps N/amp Volts meter/sec mh Newton Newton Sec mm degC/watt degC gram gram	Ohm 2.2 Volts 24 Amps 3.44 N/amp 2.35 Volts meter/sec 2.35 Volts meter/sec 2.35 Mh 0.3 Newton 7.5 Sec 0.00014 Mm 10.1 degC/watt 5 degC 155 gram 32 gram 300	Ohm 2.2 5.1 Volts 24 24 Amps 3.44 2.91 N/amp 2.35 10.4 Volts meter/sec 2.35 10.4 Mh 0.3 4.8 Newton 7.5 31.2 Newton 5.0 24 sec 0.00014 0.00094 mm 10.1 20 degC/watt 5 3 degC 155 155 gram 32 567 gram 170 595 mm 300 300



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